#include <lpc214x.h>

void delay\_ms(unsigned int count)

{

unsigned int j=0,i=0;

for(j=0;j<count;j++)

{

for(i=0;i<3000;i++);

}

}

/\* start the main program \*/

int main()

{ //PINSEL0=0x00000000;

//IODIR0=0xffffffff;

PINSEL0 = 0x000000; //Configure the P1 Pins for GPIO;

IODIR0 = 0xffffffff; //Configure the P1 pins as OUTPUT;

while(1)

{

IOSET0 = 0xffffffff; // Make all the Port pins as high

delay\_ms(1000);

IOCLR0 = 0xffffffff; // Make all the Port pins as low

delay\_ms(1000);

}

}